			··	r
L Number	Hits	Search Text	DB	Time stamp
-	27	348/208.2.ccls.	USPAT	2003/08/14 09:31
-	0	348/208.2.ccls. and inclinometer	USPAT	2003/08/13
-	1	348/208.2.ccls. and attitude	USPAT	2003/08/13
-	73	348/208.99.ccls.	USPAT	2003/08/13
-	7	348/208.99.ccls. and attitude	USPAT	2003/08/13
-	0	348/208.99.ccls. and inclinometer	USPAT	2003/08/13
-	0	348/208.99.ccls. and inclinometer	USPAT; US-PGPUB; EPO; JPO;	2003/08/13
-	30	348/208.2.ccls.	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2003/08/13 12:43
_	92	348/208.99.ccls.	USPAT; US-PGPUB; EPO; JPO;	2003/08/13 12:43
-	92	348/208.99.ccls.	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/08/13 12:43
_	10	348/208.99.ccls. and attitude	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/08/13 12:53
_	57	348/208.99.ccls. and fixed	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/08/13 12:58
-	16	348/208.99.ccls. and tripod	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2003/08/13 13:02
_	5410	optical adj encoder	IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/08/13
_	62	348/\$.ccls. and optical adj encoder	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/08/13 14:16
_	37	tripod with attitude	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2003/08/13
-	12	camera and (tripod with attitude)	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 14:23

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-	68	camera and (tripod with orientation)	USPAT;	2003/08/13
			US-PGPUB; EPO; JPO;	16:46
			DERWENT;	
			IBM TDB	
-	221	camera and inclinometer	USPAT;	2003/08/13
			US-PGPUB;	14:57
]		EPO; JPO;	
]		DERWENT; IBM TDB	1
_	209	camera and tripod and (pan same tilt)	USPAT;	2003/08/13
	203	camera and errood and (pair same error)	US-PGPUB;	15:04
			EPO; JPO;	1 2000
			DERWENT;]
			IBM_TDB	
-	127	348/211.99.ccls.	USPAT;	2003/08/13
			US-PGPUB;	15:05
	1		EPO; JPO; DERWENT;	
			IBM TDB	
_	78	348/211.99.ccls. and position	USPAT;	2003/08/13
			US-PGPUB;	15:06
			EPO; JPO;	
			DERWENT;	
		240/211 001	IBM_TDB	2002/00/12
-	24	348/211.99.ccls. and position and angle and sensor	USPAT; US-PGPUB;	2003/08/13
		and sensor	EPO; JPO;	16:31
			DERWENT;	
İ			IBM TDB	!
-	2	20030007795.pn.	USPĀT;	2003/08/13
		-	US-PGPUB;	15:08
			EPO; JPO;	
			DERWENT;	
_	2	"20010028237"	<pre>IBM_TDB USPAT;</pre>	2003/08/13
		"20010028237"	US-PGPUB;	15:09
:		20010028237.pn.	EPO; JPO;	
ŀ			DERWENT;	
			IBM_TDB	
-	486783	373/&.ccls. and position orientation	USPAT;	2003/08/13
			US-PGPUB;	16:31
			EPO; JPO; DERWENT;	
			IBM TDB	
_	0	373/&.ccls. and (position orientation)	USPAT;	2003/08/13
	1		US-PGPUB;	16:32
			EPO; JPO;	
			DERWENT;	
	1010	272/6 gglo and (monition animately)	IBM_TDB	2003/09/13
-	1912	373/\$.ccls. and (position orientation)	USPAT; US-PGPUB;	2003/08/13
			EPO; JPO;	10.52
			DERWENT;	
			IBM_TDB	
-	17	1 ,	USPĀT;	2003/08/13
		and camera	US-PGPUB;	16:33
			EPO; JPO;	
	1		DERWENT; IBM TDB	
_	2	(373/\$.ccls. and (position orientation))	USPAT;	2003/08/13
		and tripod	US-PGPUB;	16:35
		•	EPO; JPO;	
			DERWENT;	
			IBM_TDB	0000 (00 (00
-	499	1	USPAT;	2003/08/13
		orientation) and sensor and angle	US-PGPUB; EPO; JPO;	16:48
			DERWENT;	
i	İ		IBM TDB	
L				·

-	0		USPAT;	2003/08/13
		orientation) and sensor and angle and	US-PGPUB;	16:49
		@ad<=1991122	EPO; JPO;	
			DERWENT;	
			IBM TDB	
_	369	camera and tripod and (position	USPAT;	2003/08/13
		orientation) and sensor and angle and	US-PGPUB;	16:49
		@ad<=19991122	EPO; JPO;	10.19
	ļ	Gad(=13331122	DERWENT;	
				1
			IBM_TDB	
-	13	• •	USPAT	2003/08/14
		pitch and tilt and sensor		09:32
-	16	camera and tripod and pan and roll and	USPAT;	2003/08/14
		pitch and tilt and sensor	US-PGPUB;	10:25
			EPO; JPO;	
			DERWENT;	1
			IBM_TDB	2002/00/14
-	0		USPAT;	2003/08/14
		pitch and tilt and sensor and optical adj	US-PGPUB;	10:26
		encoder	EPO; JPO;	
1			DERWENT;	
	1		IBM TDB	
l -	140766	(camera and tripod and pan and roll and	USPAT;	2003/08/14
		pitch and tilt and sensor) ans encoder	US-PGPUB;	10:26
	1	proof and erro and sensor, and encoder	EPO; JPO;	10.20
	1			
	1		DERWENT;	
	1		IBM_TDB	
-	6	(camera and tripod and pan and roll and	USPAT;	2003/08/14
	1	pitch and tilt and sensor) and encoder	US-PGPUB;	14:09
	i		EPO; JPO;	
	i		DERWENT;	
	!		IBM TDB	
_	70	camera near1 stabilization	USPAT;	2003/08/14
	'*	Cample Hoult Deaptilization	US-PGPUB;	14:15
	1			14:12
	1		EPO; JPO;	
	1		DERWENT;	1
	1		IBM_TDB	
-	331	camera with gimbal	USPAT;	2003/08/14
	1		US-PGPUB;	14:16
1	1		EPO; JPO;	
	1		DERWENT;	1
	1		IBM TDB	
1_	44	(camera with gimbal) and stabilize	USPAT;	2003/08/15
	1 44	(Camera with gimbar) and Stabilize		
1			US-PGPUB;	11:54
	1		EPO; JPO;	1
			DERWENT;	
			IBM_TDB	
-	5		USPĀT	2003/08/14
	I	"5237450" "5868031").PN.		14:18
-	4	·	USPAT	2003/08/14
	1	"5184521").PN.		14:22
_	33	•	USPAT	2003/08/14
	33	J0J0J0Z. OKFN.	USEKI	
		/#2427120# 1 #2620500# 1 #4600466# 1		14:26
_	4	, , , , , , , , , , , , , , , , , , , ,	USPAT	2003/08/14
		"5184521").PN.		14:27
-	1	5868031.URPN.	USPAT	2003/08/14
				14:28
-	33	4033541.URPN.	USPAT	2003/08/14
			1	14:48
_	7	("4033541" "4052654" "5067084"	USPAT	2003/08/14
	·	"5075861" "5124938" "5169090"	UDERI	
			İ	14:56
	_	"5172323").PN.		/ /
-	7		USPAT	2003/08/14
1	1	"5075861" "5124938" "5169090"	[14:57
	1	"5172323").PN.	1	į i
-	33	4033541.URPN.	USPAT	2003/08/14
	1			14:58
_	6	3775656.URPN.	USPAT	2003/08/14
	I			14:59
L	I	<u> </u>	l	111.07

-	2	6100925.pn.	USPAT;	2003/08/15
			US-PGPUB;	12:08
			EPO; JPO;	
			DERWENT;	
		0510010	IBM_TDB	0000 (00 (05
_	0	wo9510919.pn.	USPAT;	2003/08/15
			US-PGPUB;	11:56
			EPO; JPO; DERWENT;	
			IBM TDB	
_	5	9510919.pn.	USPAT;	2003/08/15
		3310313.pm.	US-PGPUB;	11:56
			EPO; JPO;	11.30
			DERWENT;	
			IBM TDB	
_	3	inclinometer with attitude with camera	USPAT;	2003/08/15
			US-PGPUB;	12:10
			EPO; JPO;	
			DERWENT;	
	1		IBM_TDB	
-	7	(inclinometer with attitude) same camera	USPĀT;	2003/08/15
1			US-PGPUB;	12:12
1	1		EPO; JPO;	
	1		DERWENT;	1
		<u> </u>	IBM_TDB	
-	16	(inclinometer with movement) and camera	USPAT;	2003/08/15
	1		US-PGPUB;	12:14
1	1		EPO; JPO;	
			DERWENT;	
_	56	 (accelerometer with attitude) and camera	IBM_TDB USPAT;	2003/08/15
-	36	(acceletometer with attitude) and camera	US-PGPUB;	2003/08/15 12:34
	1		EPO; JPO;	14.34
	1		DERWENT;	
			IBM TDB	
-	8	(sensor with tripod adj1 head) and camera	USPAT;	2003/08/15
i		,	US-PGPUB;	12:48
1	1		EPO; JPO;	
1	l		DERWENT;	
			IBM_TDB	
-	0	(accelerometer with tripod adj1 head) and	USPAT;	2003/08/15
1		camera	US-PGPUB;	12:48
			EPO; JPO;	
1	1		DERWENT;	
1	_	[, , , , , , , , , , , , , , , , , , ,	IBM_TDB	0000 100 155
-	1	(accelerometer with tripod) and camera	USPĀT;	2003/08/15
1			US-PGPUB;	12:50
			EPO; JPO;	
1			DERWENT; IBM TDB	
_	671	(sensor with attitude) and camera	USPAT;	2003/08/15
	""	(Jenson with accitude) and Camera	US-PGPUB;	12:51
			EPO; JPO;	12.31
	1		DERWENT;	
	1		IBM TDB	
-	12	(sensor with attitude) and camera and	USPAT;	2003/08/15
		tripod	US-PGPUB;	12:51
			EPO; JPO;	
	ł		DERWENT;	
			IBM_TDB	
-	20522	,	USPĀT;	2003/08/15
[position)) and camera	US-PGPUB;	12:54
			EPO; JPO;	
	ŀ		DERWENT;	
			IBM_TDB	
-	384		USPAT;	2003/08/15
	1	position)) and camera) and tripod	US-PGPUB;	12:54
			EPO; JPO;	
			DERWENT;	
<u>L</u>	L	<u> </u>	IBM_TDB	

-	36	sensor with (camera adj (attitude))	USPAT;	2003/08/15
			US-PGPUB;	14:25
			EPO; JPO;	
			DERWENT;	1
			IBM TDB	
-	467	348/169\$.ccls.	USPAT;	2003/08/15
	1		US-PGPUB;	14:27
			EPO; JPO;	
			DERWENT;	
			IBM TDB	
-	220	348/169\$.ccls. and sensor	USPAT;	2003/08/15
			US-PGPUB;	15:50
			EPO; JPO;	
			DERWENT;	
	ļ		IBM_TDB	i
-	2	4623930.pn.	USPAT;	2003/08/15
	1		US-PGPUB;	15:57
	1		EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2	4713697.pn.	USPAT;	2003/08/15
			US-PGPUB;	15:57
			EPO; JPO;	
			DERWENT;	
			IBM TDB	